

# **GLOBAL JOURNAL OF ENGINEERING SCIENCE AND RESEARCHES** SECOND-ORDER MULTIOBJECTIVE SYMMETRIC PROGRAMMING PROBLEM AND DUALITY RELATIONS UNDER $(F, G_f)$ -CONVEXITY

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# ABSTRACT

In this paper, we introduce the definition  $(F, G_f)$ -convexity and give a nontrivial example existing such type of functions. Further, a generalization of convexity, namely  $(F, G_f)$ -convexity, is introduced in the case of non-linear multiobjective programming problems where the functions constituting vector optimization problems are differentiable. Further, second-order Wolfe type primal-dual pair has been formulated and proved weak, strong and converse duality theorems under  $(F, G_f)$ -convexity assumptions.

**Keywords:** Symmetric duality, Non-linear programming,  $(F, G_f)$ -convexity; Wolfe type model

#### I. **INTRODUCTION**

An Optimization problem is the problem of finding the best solution from all feasible solutions. Generally, all problems to be optimized should be able to be formulated as a system with its status controlled by one or more input variables and its performance specified by a well defined Objective Function. The goal of optimization is to find the best value for each variable in order to achieve satisfactory performance.Optimization is an active and fast growing research area and has a great impact on the real world.

One practical advantage of second order duality is that it provides tighter bounds for the value of the objective function of the primal problem when approximations are used because there are more parameters involved. Duality is one of the most important topic in operation research as it helps us in generating useful insights about the optimization problem. Mangasarian [11] is introduced the concept of second-order duality for nonlinear programming. Two distinct pairs of second-order symmetric dual problems under generalized bonvexity/ boncavity assumptions studied in Gulati et al. [7]. Furthermore, Gulati and Gupta [8] have been introduced the concept of  $\eta_1$ -bonvexity/ $\eta_2$ -boncavity and derived duality results for a Wolfe type model.

The concept of G-invex function has been introduced by Antczak [1] and further derived some optimality conditions for constrained optimization problem. Extended the above notion by defining a vector valued  $G_{f^-}$  invex function, Antzcak [2] proved necessary and sufficient optimality conditions for a multiobjective nonlinear programming problem. In last several years, various optimality and duality results have been obtained for multiobjective fractional programming problems. In Chen [3], multiobjective fractional problem and its duality theorems have been considered under higher-order  $(F, \alpha, \rho, d)$ - convexity. Later on, Suneja et al. [13] discussed higher-order Mond-Weir and Schaible type nondifferentiable dual programs and their duality theorems under higher-order  $(F, \rho, \sigma)$  -type Iassumptions. Recently, several researchers like (see[5, 6, 14]) have also worked in the same direction.

In this article, we have introduce the definition of  $(F, G_f)$ -convex function. Further, we construct a nontrivial numerical example which is  $(F, G_f)$ -convex but it is neither second-order F-convex nor F-convex. Also, we have consider Wolfe type multiobjective second-order symmetric dual program and establish the duality relations under





 $(F, G_f)$ - convexity assumptions.

ISSN 2348 - 8034 Impact Factor- 5.070

#### **II. NOTATIONS AND PRELIMINARIES**

Consider the following vector minimization problem:

Minimize 
$$f(x) = \left\{ f_1(x), f_2(x), ..., f_k(x) \right\}^T$$
  
Subject to  $X^0 = \{ x \in X \subset \mathbb{R}^n : g_j(x) \le 0, \ j = 1, 2, ..., m \}$ 

where  $f = \{f_1, f_2, ..., f_k\} : X \to \mathbb{R}^k$  and  $g = \{g_1, g_2, ..., g_m\} : X \to \mathbb{R}^m$  are differentiable functions defined on X.

**Definition 2.1** A point  $\bar{x} \in X^0$  is said to be an efficient solution of (MP) if there exists no other  $x \in X^0$  such that  $f_r(x) < f_r(\bar{x})$ , for some r = 1, 2, ..., k and  $f_i(x) \le f_i(\bar{x})$ , for all i = 1, 2, ..., k.

**Definition 2.2.** A functional  $F: X \times X \times R^n \to R$  is said to be sublinear with respect to the third variable if for all  $(x, u) \in X \times X$ ,

- (i)  $F_{x,u}(a_1+a_2) \leq F_{x,u}(a_1) + F_{x,u}(a_2)$ , for all  $a_1, a_2 \in \mathbb{R}^n$ ,
- (*ii*)  $F_{x,u}(\alpha a) = \alpha F_{x,u}(a)$ , for all  $\alpha \in R_+$  and  $a \in R^n$ .

Many generalizations of the definition of a convex function have been introduced in optimization theory in order to weak the assumption of convexity for establishing optimality and duality results for new classes of nonconvex optimization problems, including vector optimization problems. One of such a generalization of convexity in the vectorial case is the G-invexity notion introduced by Antczak for differentiable scalar and vector optimization problems (see [1, 2] respectively). We now generalize and extend it to the nondifferentiable vectorial case namely, motivated by Jeyakumar and Mond [12] and Antczak [2], we introduce the concept of  $(F, G_f)$ -convex.

**Definition 2.3.** Let  $f: X \to R^k$  be a vector-valued differentiable function. If there exist a sublinear functional F and differentiable function  $G_f = (G_{f_1}, G_{f_2}, ..., G_{f_k}) : R \to R^k$  such that every component  $G_{f_i} : I_{f_i}(X) \to R$  is strictly increasing on the range of  $I_{f_i}$  such that  $\forall x \in X$  and  $p \in R^n$ ,

$$\begin{aligned} G_{f_i}(f_i(x)) - G_{f_i}(f_i(u)) &\geq F_{x,u}[G'_{f_i}(f_i(u))\nabla_x f_i(u) + \{G''_{f_i}(f_i(u))\nabla_x f_i(u)(\nabla_x f_i(u))^T + G'_{f_i}(f_i(u))\nabla_{xx} f_i(u)\}p] \\ &- \frac{1}{2}p^T[G''_{f_i}(f_i(u))\nabla_x f_i(u)(\nabla_x f_i(u))^T + G'_{f_i}(f_i(u))\nabla_{xx} f_i(u)]p, \text{ for all } i = 1, 2, ..., k, \end{aligned}$$

then f is called  $(F, G_f)$ -convex at  $u \in X$ .

If the above inequality sign changes to  $\leq$ , then *f* is called  $(F, G_f)$ -concave at  $u \in X$  with respect to  $\eta$ . If the function  $f_i, i = 1, 2, ..., k$  satisfies above inequality, then we will say that  $f_i$  is  $(F, G_{f_i})$ -convex at  $u \in X$ . If the above inequalities sign changes to  $\leq$ , then *f* is called  $(F, G_f)$ -concave at  $u \in X$ .

**Remark 2.1** If  $F_{x,u}(a) = \eta^T(x, u)a$ , then Definition 2.3 becomes  $G_f$ -bonvex given by [9].

Now, we give a nontrivial example which is  $(F, G_f)$ -convex function but not F-convex function.

**Example 2.1.** Let  $f: [-1,1] \rightarrow R^2$  be defined as

 $f(x) = \{f_1(x), f_2(x)\},\$ 





ISSN 2348 - 8034 Impact Factor- 5.070



Figure 1:

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Figure 2:

where  $f_1(x) = x^3$ ,  $f_2(x) = x^4$  and  $G_f = \{G_{f_1}, G_{f_2}\} : \mathbb{R} \to \mathbb{R}^2$  be defined as:

$$G_{f_1}(t) = t^2 + 1, \ G_{f_2}(t) = t^4.$$

Let  $F: X \times X \times R^2 \to R$  be given as:

$$F_{x,u}(a) = |a|(x^2 - u^2).$$

For showing that f is  $(F, G_f)$ -convex at u = 0, for this we have to claim that

$$\begin{aligned} \pi_{i} &= G_{f_{i}}(f_{i}(x)) - G_{f_{i}}(f_{i}(u)) - F_{x,u}[G'_{f_{i}}(f_{i}(u))\nabla_{x}f_{i}(u) + \{G''_{f_{i}}(f_{i}(u))\nabla_{x}f_{i}(u)(\nabla_{x}f_{i}(u))^{T} + G'_{f_{i}}(f_{i}(u))\nabla_{xx}f_{i}(u)\}p_{i}] + \frac{1}{2}p_{i}^{T}[G''_{f_{i}}(f_{i}(u))\nabla_{x}f_{i}(u)(\nabla_{x}f_{i}(u))^{T} + G'_{f_{i}}(f_{i}(u))\nabla_{xx}f_{i}(u)]p_{i} \ge 0, \text{ for } i = 1, 2. \end{aligned}$$

Putting the values of  $f_1$ ,  $f_2$ ,  $G_{f_1}$  and  $G_{f_2}$  in the above expressions, we have

 $\pi_1 = (x^6 + 1) - (u^6 + 1) - F_{x,u}[6u^5 + \{18u^4 + 6u^5\}p_1] + \frac{1}{2}p_1^2\{18u^4 + 6u^5\},$ 190





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Figure 3:

and

$$\pi_2 = x^{16} - u^{16} - F_{x,u}(16u^{15} + \{12 \times 16u^{17} + 48u^{14}\}p_2) + \frac{1}{2}p_2^2\{12 \times 16u^{17} + 48u^{14}\},\$$

At  $u = 0 \in [-1, 1]$ , the above expressions reduces:

$$\pi_1 = x^6$$
 and  $\pi_2 = x^{16}$  for all  $x \in [-1, 1]$ 

and hence  $\pi_1 \ge 0$  and  $\pi_2 \ge 0$ , (from figures (1) and (2)), for all  $x \in [-1, 1]$ . Therefore, f is  $(F, G_f)$ -convex at u = 0. Now, suppose

$$\pi_3 = f_1(x) - f_1(u) - F_{x,u}[\nabla_x f_1(u) + \nabla_{xx} f_1(u) p_1] + \frac{1}{2} p_1^T [\nabla_{xx} f_1(u)] p_1.$$

or

$$\pi_3 = x^3 - u^3 - F_{x,u}[3u^2 + 6up_1] + 3up_1^2$$

which at u = 0 yields

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$$\pi_3 = x^3$$
, for all  $x \in [-1, 1]$   
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Obviously,

$$\pi_3 \not\geq 0, \ \left( \text{from figure } (3) \right).$$

Therefore,  $f_1$  is not second-order *F*-convex at u = 0 with respect to *p*. Hence,  $f = (f_1, f_2)$  is not second-order *F*-convex at u = 0 with respect to *p*. Finally, consider

$$\xi = f_1(x) - f_1(u) - F_{x,u}(\nabla_x f_1(u))$$

or

$$\xi = x^3 - u^3 - F_{x,u}(3u^2)$$

which at u = 0 and using sublinearity of functional *F*, we get

$$\xi = x^3$$
.

At the point  $x = \frac{-1}{3} \in [-1, 1]$ , obtain

$$\xi = \frac{-1}{27} \ngeq 0.$$

Therefore,  $f_1$  is not *F*-convex at u = 0. Hence,  $f = (f_1, f_2)$  is not *F*-convex at u = 0.

#### III. WOLFE TYPE SYMMETRIC DUAL PROGRAM

Consider the following pair of Wolfe type dual program: **Primal problem (WP):** 

Minimize  $R(x, y, \lambda, p) = \left(R_1(x, y, \lambda_1, p), R_2(x, y, \lambda_2, p), \dots R_k(x, y, \lambda_k, p)\right)^T$ 

Subject to

$$\sum_{i=1}^{k} \lambda_{i} \bigg[ G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) + \{ G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y) \} p \bigg] \leq 0,$$
(1)

$$\lambda > 0, \ \lambda^T e_k = 1. \tag{2}$$

Dual problem (WD):

Maximize  $S(u, v, \lambda, q) = \left(S_1(u, v, \lambda_1, q), S_2(u, v, \lambda_2, q), \dots, S_k(u, v, \lambda_k, q)\right)^T$ 

Subject to

$$\sum_{i=1}^{k} \lambda_i \bigg[ G'_{f_i}(f_i(u,v)) \nabla_x f_i(u,v) + \{ G''_{f_i}(f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v))^T + G'_{f_i}(f_i(u,v)) \nabla_{xx} f_i(u,v) ) \} q \bigg] \ge 0,$$
(3)

$$\lambda > 0, \ \lambda^T e_k = 1, \tag{4}$$



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where for all i = 1, 2, ..., k,

[*Dubey et al.* 5(8): August 2018] DOI: 10.5281/zenodo.1341853 ISSN 2348 - 8034 Impact Factor- 5.070

$$\begin{aligned} R_{i}(x,y,\lambda,p) &= G_{f_{i}}(f_{i}(x,y)) - y^{T} \sum_{i=1}^{k} \lambda_{i} \left( G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) + [G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y)] p \right) \\ &- \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} p^{T} \left( G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y) \right) p, \\ S_{i}(u,v,\lambda,q) &= G_{f_{i}}(f_{i}(u,v)) - u^{T} \sum_{i=1}^{k} \lambda_{i} \left( G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) + [G''_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \nabla_{xx} f_{i}(u,v)] q \right) \\ &- \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} q^{T} \left( G''_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \nabla_{xx} f_{i}(u,v) \right) q, \end{aligned}$$

(*i*)  $f_i$  and  $G_{f_i}$  are differentiable functions in x and y,  $e_k = (1, 1, ..., 1)^T \in \mathbb{R}^k$ , (*ii*)  $p_i$  and  $q_i$  are vectors in  $\mathbb{R}^m$  and  $\mathbb{R}^n$ , respectively,  $\lambda \in \mathbb{R}^k$ .

The following example shows the feasibility of the (WP) and (WD) problem discussed above:

**Example 3.1** Let k = 2. Let  $f_i : X \times Y \to R$  be defined as

$$f_1(x,y) = x^3, f_2(x,y) = y^3$$

Suppose  $G_{f_i}(t) = t, i = 1, 2.$ 

#### (EWP) Minimize

 $R(x,y) = (x^3 - y\lambda_2[3y^2 + 6yp] - 3\lambda_2yp^2, y^3 - y\lambda_2[3y^2 + 6yp] - 3\lambda_2yp^2)$ 

Subject to

$$\lambda_2(3y^2+6yp) \le 0,$$
  
 $\lambda_1, \lambda_2 > 0, \lambda_1+\lambda_2 = 1$ 

#### (EWD) Maximize

 $S(u,v) = (u^3 - u\lambda_1[3u^2 + 6uq] - 3\lambda_1q^2u, v^3 - u\lambda_1[3u^2 + 6uq] - 3\lambda_1q^2u)$ 

Subject to

$$\begin{split} \lambda_1[3u^2+6uq] &\geq 0, \\ \lambda_1,\lambda_2 &> 0, \lambda_1+\lambda_2 = 1. \end{split}$$

One can easily verify that  $x = 3, y = 0, \lambda_1 = \frac{1}{2}, \lambda_2 = \frac{1}{2}, p = 2$  is a feasible solution of primal problem and  $u = 0, v = \frac{1}{3}, \lambda_1 = \frac{1}{2}, \lambda_2 = \frac{1}{2}, q = 1$  is a feasible solution of dual problem. This shows that such primal-dual pair (EWP) and (EWD) exist.

Next, we prove duality theorems for the pair (WP) and (WD).

**Theorem 3.1** (Weak duality theorem). Let  $(x, y, \lambda, p)$  and  $(u, v, \lambda, q)$  be feasible solutions of primal and dual problem, respectively. Let for all i = 1, 2, ..., k, 193





(i)  $f_i(.,v)$  be  $(F,G_{f_i})$ -convex at u,

(*ii*)  $f_i(x,.)$  be  $(H, G_{f_i})$ - concave at y,

where the sublinear functionals  $F : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$  and  $H : \mathbb{R}^m \times \mathbb{R}^m \to \mathbb{R}$  satisfy the following conditions:

- (iii)  $F_{x,u}(a) + a^T u \ge 0, \forall a \in \mathbb{R}^n_+,$
- (*iv*)  $H_{v,y}(b) + b^T y \ge 0, \forall b \in R^m_+.$

Then, the following cannot hold:

$$R_i(x, y, \lambda, p) \le S_i(u, v, \lambda, q), \text{ for all } i = 1, 2, \dots, k$$
(5)

and

$$R_r(x, y, \lambda, p) < S_r(u, v, \lambda, q), \text{ for some } r = 1, 2, \dots, k.$$
(6)

**Proof.** Suppose on the contrary that (5) and (6) hold. Then, using  $\lambda > 0$ , we obtain

$$\sum_{i=1}^{k} \lambda_{i} \bigg[ G_{f_{i}}(f_{i}(x,y)) - y^{T} \sum_{i=1}^{k} \lambda_{i} \bigg( G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) + G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \bigg) \\ \nabla_{yy} f_{i}(x,y) \bigg] p \bigg) - \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} \bigg( p^{T} [G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y)] p \bigg) \bigg] \\ < \sum_{i=1}^{k} \lambda_{i} \bigg[ G_{f_{i}}(f_{i}(u,v)) - u^{T} \sum_{i=1}^{k} \lambda_{i} \bigg( G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) + G''_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \bigg] \\ \nabla_{xx} f_{i}(u,v) \bigg] q \bigg) - \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} \bigg( q^{T} [G''_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \nabla_{xx} f_{i}(u,v)] q \bigg) \bigg].$$
(7)

Since  $f_i(.,v)$  is  $(F, G_{f_i})$ -convex at u, we get

$$G_{f_{i}}(f_{i}(x,v)) - G_{f_{i}}(f_{i}(u,v)) \ge F_{x,u}[G'_{f_{i}}(f_{i}(u,v))\nabla_{x}f_{i}(u,v) + \{G''_{f_{i}}(f_{i}(u,v))\nabla_{x}f_{i}(u,v)(\nabla_{x}f_{i}(u,v))(\nabla_{x}f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v))\nabla_{x}f_{i}(u,v)(\nabla_{x}f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v))\nabla_{x}f_{i}(u,v)]q.$$

Since  $\lambda > 0$  and using sublinearity of *F* at the third position, the above inequality yields

$$\sum_{i=1}^{k} \lambda_{i} \Big[ G_{f_{i}}(f_{i}(x,v)) - G_{f_{i}}(f_{i}(u,v)) \Big] \ge F_{x,u} \Big\{ \sum_{i=1}^{k} \lambda_{i} \Big[ G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) + \{ G''_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))$$

Further, using hypothesis (*iii*) and dual constraint (3), we get

$$\sum_{i=1}^{k} \lambda_i \Big[ G_{f_i}(f_i(x,v)) - G_{f_i}(f_i(u,v)) \Big] \ge -u^T \sum_{i=1}^{k} \lambda_i \Big[ G'_{f_i}(f_i(u,v)) \nabla_x f_i(u,v) + \{ G''_{f_i}(f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v)) \nabla_x f_i(u,v) \Big] \\ + G'_{f_i}(f_i(u,v)) \nabla_{xx} f_i(u,v) \Big] - \frac{1}{2} \sum_{i=1}^{k} \lambda_i q^T \Big[ G''_{f_i}(f_i(u,v)) \nabla_x f_i(u,v) (\nabla_x f_i(u,v))^T + G'_{f_i}(f_i(u,v)) \nabla_{xx} f_i(u,v) \Big] q. \quad (8)$$

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Similarly, using hypotheses (i), (iv) and dual constraint (1), we get

$$\sum_{i=1}^{k} \lambda_{i} \Big[ -G_{f_{i}}(f(x,y)) + G_{f_{i}}(f_{i}(x,y)) \Big] \ge y^{T} \sum_{i=1}^{k} \lambda_{i} \Big[ G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) + \{ G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y)) \nabla_{y} f_{i}(x,y) \}^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y) \Big\} p \Big] + \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} p^{T} \Big[ G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y) \Big] p.$$
(9)

Finally, adding inequalities (8), (9) and  $\lambda^T e_k = 1$ , we get

$$\begin{split} \sum_{i=1}^{k} \lambda_{i} \bigg[ G_{f_{i}}(f_{i}(x,y)) - y^{T} \sum_{i=1}^{k} \lambda_{i} \bigg( G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) + G'_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \\ \nabla_{yy} f_{i}(x,y) ] p \bigg) &- \frac{1}{2} \sum_{i=1}^{k} \lambda_{i} \bigg( p^{T} [G''_{f_{i}}(f_{i}(x,y)) \nabla_{y} f_{i}(x,y) (\nabla_{y} f_{i}(x,y))^{T} + G'_{f_{i}}(f_{i}(x,y)) \nabla_{yy} f_{i}(x,y)] p \bigg) \bigg] \\ &\geq \sum_{i=1}^{k} \lambda_{i} \bigg[ G_{f_{i}}(f_{i}(u,v)) - u^{T} \sum_{i=1}^{k} \lambda_{i} \bigg( G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) + G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \bigg] \bigg] \\ &\sum_{i=1}^{k} \lambda_{i} \bigg[ G_{f_{i}}(f_{i}(u,v)) - u^{T} \sum_{i=1}^{k} \lambda_{i} \bigg( G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) + G'_{f_{i}}(f_{i}(u,v)) \nabla_{x} f_{i}(u,v) (\nabla_{x} f_{i}(u,v))^{T} + G'_{f_{i}}(f_{i}(u,v)) \bigg] \bigg] \bigg] . \end{split}$$

This contradicts (7). Hence, the result.

**Theorem 3.2 (Strong duality).** Let  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{p})$  be an efficient solution of (WP); fix  $\lambda = \bar{\lambda}$  in (WD) such that

(*i*) for all 
$$i = 1, 2, ..., k$$
,  $[G''_{f_i}(f_i(\bar{x}, \bar{y}))\nabla_y f_i(\bar{x}, \bar{y})(\nabla_y f_i(\bar{x}, \bar{y}))^T + G'_{f_i}(f_i(\bar{x}, \bar{y}))\nabla_{yy} f_i(\bar{x}, \bar{y})]$  is nonsingular,

$$\begin{array}{ll} (ii) & \sum_{i=1}^{k} \bar{\lambda}_{i} \nabla_{y} \bigg( \{ G_{f_{i}}^{\prime\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G_{f_{i}}^{\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y}) \} \bar{p} \bigg) \bar{p} \\ & \notin \operatorname{span} \bigg\{ G_{f_{1}}^{\prime}(f_{1}(\bar{x},\bar{y})) \nabla_{y} f_{1}(\bar{x},\bar{y}), ..., G_{f_{k}}^{\prime}(f_{k}(\bar{x},\bar{y})) \nabla_{y} f_{k}(\bar{x},\bar{y}) \bigg\} \setminus \{0\}, \\ (iii) & \text{the vectors} \bigg\{ G_{f_{1}}^{\prime}(f_{1}(\bar{x},\bar{y})) \nabla_{y} f_{1}(\bar{x},\bar{y}), G_{f_{2}}^{\prime}(f_{2}(\bar{x},\bar{y})) \nabla_{y} f_{2}(\bar{x},\bar{y}), ..., G_{f_{k}}^{\prime}(f_{k}(\bar{x},\bar{y})) \nabla_{y} f_{k}(\bar{x},\bar{y}) \bigg\} \text{ are linearly independent,} \end{array}$$

$$(iv) \sum_{i=1}^{k} \bar{\lambda}_{i} \nabla_{y} \bigg( \{ G_{f_{i}}^{\prime\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G_{f_{i}}^{\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y}) \} \bar{p} \bigg) \bar{p} = 0 \Rightarrow \bar{p} = 0.$$

Then,  $\bar{q} = 0$  such that  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{q} = 0)$  is feasible solution for (WD) and the value of objective functions are equal. Also, if the assumptions of weak duality theorem hold, then  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{q} = 0)$  is an efficient solution for (WD).

**Proof.** Since  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{p})$  is an efficient solution of (WP), using Fritz -John necessary conditions [4], then there exist  $\alpha \in \mathbb{R}^k$ ,  $\beta \in \mathbb{R}^m$  and  $\eta \in \mathbb{R}$  such that

$$\sum_{i=1}^{k} \alpha_{i} [G'_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{x} f_{i}(\bar{x},\bar{y})] + \sum_{i=1}^{k} \bar{\lambda}_{i} \left[ G''_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) \nabla_{x} f_{i}(\bar{x},\bar{y}) + G'_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{xy} f_{i}(\bar{x},\bar{y}) \right] \left( \beta - (\alpha^{T} e_{k}) \bar{y} \right) \\ + \sum_{i=1}^{k} \bar{\lambda}_{i} \nabla_{x} \left[ (G''_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G'_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y})) \bar{p} \right] \left( \beta - (\alpha^{T} e_{k}) (\bar{y} + \frac{1}{2} \bar{p}) \right) = 0, \quad (10)$$

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# $\begin{bmatrix} Dubey et al. 5(8): August 2018] & ISSN 2348 - 8034 \\ Impact Factor - 5.070 \\ \sum_{i=1}^{k} \left( \alpha_{i} - (\alpha^{T} e_{k}) \bar{\lambda}_{i} \right) \left[ G'_{f_{i}}(f_{i}(\bar{x}, \bar{y})) \nabla_{y} f_{i}(\bar{x}, \bar{y}) \right] + \sum_{i=1}^{k} \bar{\lambda}_{i} \left[ \left\{ G''_{f_{i}}(f_{i}(\bar{x}, \bar{y})) \nabla_{y} f_{i}(\bar{x}, \bar{y}) \right\}^{T} \\ + G'_{f_{i}}(f_{i}(\bar{x}, \bar{y})) \nabla_{yy} f_{i}(\bar{x}, \bar{y}) \right\} \left( \beta - (\alpha^{T} e_{k})(\bar{y} + \bar{p}) \right) + \sum_{i=1}^{k} \bar{\lambda}_{i} \left[ \nabla_{y} \{ G''_{f_{i}}(f_{i}(\bar{x}, \bar{y})) \nabla_{y} f_{i}(\bar{x}, \bar{y}) \right]^{T} \\ + G'_{f_{i}}(f_{i}(\bar{x}, \bar{y})) \nabla_{yy} f_{i}(\bar{x}, \bar{y})) \nabla_{yy} f_{i}(\bar{x}, \bar{y}) \rho_{y} \rho_$

$$\left[G_{f_{i}}^{\prime\prime}(f_{i}(\bar{x},\bar{y}))\nabla_{y}f_{i}(\bar{x},\bar{y})(\nabla_{y}f_{i}(\bar{x},\bar{y}))^{T}+G_{f_{i}}^{\prime}(f_{i}(\bar{x},\bar{y}))\nabla_{yy}f_{i}(\bar{x},\bar{y})\right]\left[\left(\beta-(\alpha^{T}e_{k})(\bar{p}+\bar{y})\right)\bar{\lambda}_{i}\right]=0,\ i=1,2,...,k,\quad(12)$$

$$G'_{f}(f(\bar{x},\bar{y}))\nabla_{y}f(\bar{x},\bar{y})\left(\beta - (\alpha^{T}e_{k}\bar{y})\right) + \eta e_{k} + \left\{\left(\beta - (\alpha^{T}e_{k})(\bar{y} + \frac{1}{2}\bar{p}_{1})\right)^{T}\left(G''_{f_{1}}(f_{1}(\bar{x},\bar{y}))\nabla_{y}f_{1}(\bar{x},\bar{y})(\nabla_{y}f_{1}(\bar{x},\bar{y}))^{T} + G'_{f_{1}}(f_{1}(\bar{x},\bar{y}))\nabla_{yy}f_{1}(\bar{x},\bar{y}))\bar{p}_{1}\right), ..., \left(\beta - (\alpha^{T}e_{k})(\bar{y} + \frac{1}{2}\bar{p}_{k})\right)^{T}\left(G''_{f_{k}}(f_{k}(\bar{x},\bar{y}))\nabla_{y}f_{k}(\bar{x},\bar{y})(\nabla_{y}f_{k}(\bar{x},\bar{y}))^{T} + G'_{f_{k}}(f_{k}(\bar{x},\bar{y}))\nabla_{yy}f_{k}(\bar{x},\bar{y}))\nabla_{y}f_{k}(\bar{x},\bar{y})\right) = 0,$$
(13)

$$\beta^{T} \sum_{i=1}^{k} \bar{\lambda}_{i} [G'_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) + \{G''_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{x} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G'_{f_{i}}(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y})\} \bar{p}] = 0, \quad (14)$$

$$\eta^T [\bar{\lambda}^T e_k - 1] = 0, \tag{15}$$

$$(\alpha,\beta) \ge 0, \ (\alpha,\beta,\eta) \ne 0.$$
 (16)

Equation (13) can be written as

$$G'_{f_{i}}(f_{i}(\bar{x},\bar{y}))\nabla_{y}f_{i}(\bar{x},\bar{y})\left(\beta - (\alpha^{T}e_{k})\bar{y}\right) + \left(\beta - (\alpha^{T}e_{k})(\bar{y} + \frac{1}{2}\bar{p})\right)^{T}\left((G''_{f_{i}}(f_{i}(\bar{x},\bar{y}))\nabla_{y}f_{i}(\bar{x},\bar{y})(\nabla_{y}f_{i}(\bar{x},\bar{y}))^{T} + G'_{f_{i}}(f_{i}(\bar{x},\bar{y}))\nabla_{yy}f_{i}(\bar{x},\bar{y}))\bar{p}\right) + \eta = 0, \ i = 1, 2, ..., k.$$
(17)

By hypothesis (*i*) and  $\bar{\lambda}_i > 0$ , for i = 1, 2, ..., k, (12) gives

$$\beta = (\alpha^T e_k)(\bar{p} + \bar{y}), \ i = 1, 2, ..., k.$$
(18)

If  $\alpha = 0$ , then (18) implies that  $\beta = 0$ . Further, equation (17) gives  $\eta = 0$ . Consequently,  $(\alpha, \beta, \eta) = 0$ , which contradicts (16). Hence,  $\alpha \neq 0$ , or  $\alpha^T e_k > 0$ .

Using (18) and  $\alpha^T e_k > 0$  in (11), we get

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$$\sum_{i=1}^{k} \bar{\lambda}_{i} \left[ \left( \nabla_{y} \left\{ (G_{f_{i}}^{\prime\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G_{f_{i}}^{\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y})) \bar{p} \right\} \bar{p} \right) \right]$$

$$= -\frac{2}{\alpha^{T} e_{k}} \sum_{i=1}^{k} \left[ G_{f_{i}}^{\prime\prime}(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) \right] \left( \alpha_{i} - (\alpha^{T} e_{k}) \bar{\lambda}_{i} \right).$$

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$$(19)$$





It follows from hypothesis (ii) that

$$\sum_{i=1}^{k} \bar{\lambda}_{i} \left[ \left( \nabla_{y} \left\{ \left( G_{f_{i}}''(f_{i}(\bar{x},\bar{y})) \nabla_{y} f_{i}(\bar{x},\bar{y}) (\nabla_{y} f_{i}(\bar{x},\bar{y}))^{T} + G_{f_{i}}'(f_{i}(\bar{x},\bar{y})) \nabla_{yy} f_{i}(\bar{x},\bar{y}) ) \bar{p} \right\} \bar{p} \right) \right] = 0.$$
(20)

Hence, by hypothesis (iv), we obtain

$$\bar{p} = 0. \tag{21}$$

Therefore, the inequality (18) implies

$$\beta = (\alpha^T e_k) \bar{y}. \tag{22}$$

Now, using (21) in (19), we obtain

$$\sum_{i=1}^k \left( \alpha_i - (\alpha^T e_k) \bar{\lambda}_i \right) [G'_{f_i}(f_i(\bar{x}, \bar{y})) \nabla_y f_i(\bar{x}, \bar{y})] = 0.$$

From hypothesis (iii), it yields

$$\boldsymbol{\alpha}_i = (\boldsymbol{\alpha}^T \boldsymbol{e}_k) \bar{\boldsymbol{\lambda}}_i, \ i = 1, 2, \dots, k.$$
<sup>(23)</sup>

Using  $\alpha^T e_k > 0$ , (21)-(23) in (10), we get

$$\bar{x}^T \sum_{i=1}^k \bar{\lambda}_i \bigg[ G'_{f_i}(f_i(\bar{x}, \bar{y})) \nabla_x f_i(\bar{x}, \bar{y})] \bigg] = 0.$$

Further, using (14),  $\alpha^T e_k > 0$ , (21) and (22), we have

$$\bar{y}^T \sum_{i=1}^k \bar{\lambda}_i \bigg[ G'_{f_i}(f_i(\bar{x}, \bar{y})) \nabla_x f_i(\bar{x}, \bar{y})] \bigg] = 0.$$
(24)

Hence,  $(\bar{x}, \bar{y}, \bar{\lambda}, \bar{q} = 0)$  satisfies the constraints (3) and (4) of (WD) and clearly a feasible solution for the dual problem (WD). Hence, the result.

**Theorem 3.3** (Converse duality). Let  $(\bar{u}, \bar{v}, \bar{\lambda}, \bar{q})$  be an efficient solution of (WD); fix  $\lambda = \bar{\lambda}$  in (WP) such that

(*i*) for all i = 1, 2, ..., k,  $[G''_{f_i}(f_i(\bar{u}, \bar{v}))\nabla_x f_i(\bar{u}, \bar{v})(\nabla_x f_i(\bar{u}, \bar{v}))^T + G'_{f_i}(f_i(\bar{u}, \bar{v}))\nabla_{xx} f_i(\bar{u}, \bar{v})]$  is nonsingular,

$$\begin{array}{l} (ii) \quad \sum_{i=1}^{k} \bar{\lambda}_{i} \nabla_{x} \left( \{ G_{f_{i}}^{\prime\prime}(f_{i}(\bar{u},\bar{v})) \nabla_{x} f_{i}(\bar{u},\bar{v}) (\nabla_{x} f_{i}(\bar{u},\bar{v}))^{T} + G_{f_{i}}^{\prime}(f_{i}(\bar{u},\bar{v})) \nabla_{xx} f_{i}(\bar{u},\bar{v}) \} \bar{q} \right) \bar{q} \\ \notin \operatorname{span} \left\{ G_{f_{1}}^{\prime}(f_{1}(\bar{u},\bar{v})) \nabla_{x} f_{1}(\bar{u},\bar{v}), \dots, G_{f_{k}}^{\prime}(f_{k}(\bar{u},\bar{v})) \nabla_{x} f_{k}(\bar{u},\bar{v}) \right\} \setminus \{0\}, \\ (iii) \quad \operatorname{the vectors} \left\{ G_{f_{1}}^{\prime}(f_{1}(\bar{u},\bar{v})) \nabla_{x} f_{1}(\bar{u},\bar{v}), G_{f_{2}}^{\prime}(f_{2}(\bar{u},\bar{v})) \nabla_{x} f_{2}(\bar{u},\bar{v}), \dots, G_{f_{k}}^{\prime}(f_{k}(\bar{u},\bar{v})) \nabla_{x} f_{k}(\bar{u},\bar{v}) \right\} \text{ are linearly independent,} \\ (iv) \quad \sum_{i=1}^{k} \bar{\lambda}_{i} \nabla_{x} \left( \{ G_{f_{i}}^{\prime\prime}(f_{i}(\bar{u},\bar{v})) \nabla_{x} f_{i}(\bar{u},\bar{v}) (\nabla_{x} f_{i}(\bar{u},\bar{v}))^{T} + G_{f_{i}}^{\prime}(f_{i}(\bar{u},\bar{v})) \nabla_{xx} f_{i}(\bar{u},\bar{v}) \} \bar{q} \right) \bar{q} = 0 \Rightarrow \bar{q} = 0. \end{array}$$

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# ISSN 2348 - 8034 Impact Factor- 5.070

Then,  $\bar{p} = 0$  such that  $(\bar{u}, \bar{v}, \bar{\lambda}, \bar{p} = 0)$  is feasible solution of (WP) and  $R(\bar{u}, \bar{v}, \bar{\lambda}, \bar{p}) = S(\bar{u}, \bar{v}, \bar{\lambda}, \bar{p})$ . Also, if the hypotheses of Theorem 3.1 hold, then  $(\bar{u}, \bar{v}, \bar{\lambda}, \bar{p} = 0)$  is an efficient solution for (WP).

**Proof.** It follows on the lines of Theorem 3.2.

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